

Constructing Generalized Gelfand-Graev Representations

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Number theory and L-functions

Number theory is one of the most ancient branches of mathematics.

Examples of L-functions:

- Riemann-Zeta function

$$\zeta(s) = \sum_{n=1}^{\infty} \frac{1}{n^s}$$

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- Dirichlet L-function

$$L(s, \chi) = \sum_{n=1}^{\infty} \frac{\chi(n)}{n^s}$$

Number theory and L-functions

Birch and Swinnerton-Dyer conjecture

- Hasse-Weil L-function

$$L(s, E) = \prod_p \frac{1}{1 - a_p p^{-s} + p^{1-2s}}$$

Representation Theory

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- A representation of a group G is a linear group action of G on a vector space V , called the representation space.
- A group action of a group G on a set A is a map from $G \times A$ to A such that:
 - $g_1 \cdot (g_2 \cdot a) = (g_1 g_2) \cdot a$ for all g_1, g_2 in G , a in A
 - $1 \cdot a = a$ for all a in A

Representation of S_3 on \mathbb{R}^3

- S_3 acts on vectors in \mathbb{R}^3 by permuting their coordinates.
- For example: $(123) \cdot \langle x, y, z \rangle = \langle z, x, y \rangle$ and
 $(23) \cdot \langle x, y, z \rangle = \langle x, z, y \rangle$

Representation of S_3 on \mathbb{R}^3

The action of S_3 on \mathbb{R}^3 can be understood by looking at specific subspaces that are stable under the group action:

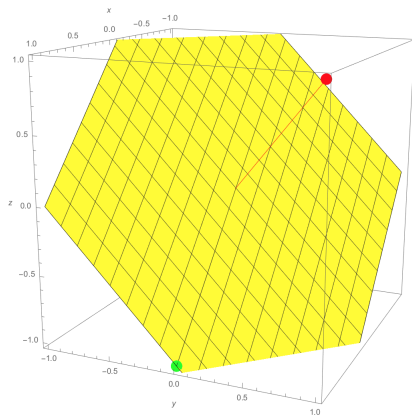
- The span of a vector $w = \langle 1, 1, 1 \rangle$
- Vectors whose coordinates add to 0, that live in the plane $x + y + z = 0$.

Representation of S_3 on \mathbb{R}^3

The action of S_3 on the vector $\langle 1, 2, 3 \rangle$ can be understood by expressing $\langle 1, 2, 3 \rangle$ as a linear combination of w and vectors whose coordinates add to 0.

$$\langle 1, 2, 3 \rangle = \langle -1, 0, 1 \rangle + \langle 2, 2, 2 \rangle$$

Representation of S_3 on \mathbb{R}^3



Generalized Gelfand-Graev Representations

- Generalized Gelfand-Graev representations (GGGRs) have originally been introduced by Kawanaka in 1985.
- They are important for integral realizations of automorphic L-functions.
- The main result of our project sheds light on the construction of GGGRs in the case of $GL(n)$ defined over finite fields.

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- $Z_L = Z_L(A) = \{\ell \in L_A \mid \ell A \ell^{-1} = A\}$
- $(\eta, V) =$ a representation of $U_A Z_L$

GGGRs

$$\text{Ex: } A = \begin{pmatrix} 0 & & 1 \\ & 0 & \\ & & 0 \end{pmatrix} \quad L = \begin{pmatrix} * & & \\ & * & \\ & & * \end{pmatrix}$$

$$U_A = \begin{pmatrix} 1 & * & * \\ & 1 & * \\ & & 1 \end{pmatrix} \quad Z_L = \begin{pmatrix} x & & \\ & y & \\ & & x \end{pmatrix}$$

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An induced representation is a representation of G built from a representation of a subgroup.

Nilpotent matrices

A matrix A is **nilpotent** if $A^n = 0$ for some $n > 0$.

- Ex: $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $A^2 = 0$

Example of a Nilpotent Orbit

A nilpotent orbit is a set \mathcal{O} of nilpotent matrices such that for any A, B in \mathcal{O} , $A = gBg^{-1}$ for some g in G .

Example of a Nilpotent Orbit

Orbit Representative
$\begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix}$
Other Matrices in the Orbit
$\begin{pmatrix} 0 & 1 & 0 \\ -2 & -4 & 2 \\ -4 & -7 & 4 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 2 & 4 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 2 & 4 & 1 \end{pmatrix}^{-1}$
$\begin{pmatrix} -5 & -7 & -2 \\ 3 & 4 & 1 \\ 1 & 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & -2 & 0 \\ -1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 \end{pmatrix} \begin{pmatrix} 1 & -2 & 0 \\ -1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}^{-1}$

Partitions and Nilpotent Orbits

- A partition of n is a way of expressing n as a sum of positive integers, i.e. $[\lambda_1, \dots, \lambda_r]$ such that $\lambda_1 + \dots + \lambda_r = n$.
 - Ex: a partition of 5: $[3, 2]$
- Nilpotent orbits are in bijective correspondence with partitions of n .
- Our choice of the nilpotent orbit representative is determined by having the semisimple element in dominance order.

Partitions and Nilpotent Orbits

Partition = [3, 1]

Semisimple Element	Nilpotent Orbit Representative
$\begin{pmatrix} 2 & & & \\ & 0 & & \\ & & -2 & \\ & & & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 1 & & \\ & 0 & 1 & \\ & & 0 & \\ & & & 0 \end{pmatrix}$
$\begin{pmatrix} 2 & & & \\ & 0 & & \\ & & 0 & \\ & & & -2 \end{pmatrix}$	$\begin{pmatrix} 0 & 1 & & \\ & 0 & & 1 \\ & & 0 & \\ & & & 0 \end{pmatrix}$

Result

Theorem

Let $G = \mathrm{GL}(n, \mathbb{F}_q)$. Let Γ_λ be the GGGR corresponding to the partition $\lambda = [\lambda_1^{k_1}, \dots, \lambda_r^{k_r}]$. Then Z_L is a subgroup of G consisting of λ_i identical $\mathrm{GL}(k_i)$ blocks on the diagonal.

Theorem in action

Partition	Nilpotent Orbit Representative	Z_L
$[3, 2]$	$\begin{pmatrix} 0 & & 1 & & \\ & 0 & & 1 & \\ & & 0 & & 1 \\ & & & 0 & \\ & & & & 0 \end{pmatrix}$	$\begin{pmatrix} v & & & & \\ & u & & & \\ & & v & & \\ & & & u & \\ & & & & v \end{pmatrix}$
$[2, 1^3]$	$\begin{pmatrix} 0 & & & & 1 \\ & 0 & & & \\ & & 0 & & \\ & & & 0 & \\ & & & & 0 \end{pmatrix}$	$\begin{pmatrix} x & & & & \\ \hline & & & & \\ & & A & & \\ \hline & & & & \\ & & & & x \end{pmatrix}$

Justification for the Theorem

Given $[2^2]$, arrange the nilpotent orbit representative in blocks corresponding to the partition and assign variables along the diagonal for each block.

$$\left(\begin{array}{cc|cc} 0 & 1 & & \\ & 0 & & \\ \hline & & 0 & 1 \\ & & & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|cc} x & & & \\ & x & & \\ \hline & & y & \\ & & & y \end{array} \right)$$

Justification for the Theorem

The nilpotent orbit representative of the partition determines the correct positions of the variables in Z_L . Repeating patterns of n variables indicate a $GL(n)$ block in Z_L .

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Justification for the Theorem

The nilpotent orbit representative of the partition determines the correct positions of the variables in Z_L . Repeating patterns of n variables indicate a $GL(n)$ block in Z_L .

$$\begin{pmatrix} 0 & 1 & \\ & 0 & 1 \\ & & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} x & & & \\ & y & & \\ & & x & \\ & & & y \end{pmatrix}$$

$$\rightarrow Z_L = \left(\begin{array}{c|c} A & \\ \hline & A \end{array} \right)$$

Further Research

The matrix coefficients that appear in integral representations of some L-functions come from groups other than $GL(n)$. With this in mind, we have the following plans for future research:

- Find a formula for Z_L for other finite groups of Lie type, e.g. $SO(2n + 1)$, $Sp(2n)$, $SO(2n)$.
- For the groups above, find a formula for $U_{1.5}$ (such a formula is known for $GL(n)$)

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